
mathMB

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mathMB provides mathematical functions designed to be used by nexoclom, although they can be used as stand-alone routines.

INTERPU

`interpu()`: 1D linear interpolation using astropy quantities.

This is a wrapper for `numpy.interp` for use when using astropy quantities. If `x` and `xp` have different units, `xp` is converted to the units of `x` before interpolation. An exception is raised if the units are not compatible (i.e., the units of `xp` cannot be converted to the units of `x`).

Author Matthew Burger

`mathMB.interpu.interpu(x, xp, fp, **kwargs)`
Return one dimensional interpolated astropy quantities.

Parameters

x The x-coordinates at which to evaluate the interpolated values

xp The x-coordinates of the data points.

fp The y-coordinates of the data points

Notes

`x` and `xp` must have compatible units. See [numpy.interp](#) for details on interpolation.

MINMAXMEAN

`minmaxmean()`: Print `np.min()`, `np.max()`, `np.mean()` at once.

`mathMB.minmaxmean.minmaxmean(x)`

Print `np.min()`, `np.max()`, `np.mean()` at once.

RANDOMDEVIATES

Compute random deviates from arbitrary 1D and 2D distributions.

`mathMB.randomdeviates.random_deviates_1d(x, f_x, num)`

Compute random deviates from arbitrary 1D distribution.

`f_x` does not need to integrate to 1. The function normalizes the distribution. Uses Transformation method (Numerical Recipes, 7.3.2)

Parameters

x The x values of the distribution

f_x The relative probability of the value being in x and x+dx

num The number of random deviates to compute

Returns

numpy array of length num chosen from the distribution `f_x`.

`mathMB.randomdeviates.random_deviates_2d(fdist, x0, y0, num)`

Compute random deviates from arbitrary 2D distribution.

Uses acceptance/rejection method. **Parameters**

fdist 2d array of relative probability

x0 xaxis

y0 yaxis

num number of points to choose

Outputs

x, y vectors of length num

ROTATION_MATRIX

`rotation_matrix()`: Compute the rotation matrix about an axis.

`mathMB.rotation_matrix.rotation_matrix(theta, axis)`

Compute the rotation matrix for a rotation of θ about axis.

Authors Matthew Burger

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